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Problem #1

Determine the maximum shear stress and rate of twist of the given shaft if a 10 kNm torque is applied to it.

If the length of the shaft is 15 m, how much

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supply chains
and the way
individuals are
circumscribed by
the systems in
which they act.

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procedure
compare with
those obtained

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in Problems 2
and 4?

SOLUTIONS: See
table and plots.
Compare ...

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Problem1. Let

Z be the set of
integers.

Determine all

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functions $f: \mathbb{Z} \rightarrow \mathbb{Z}$ such that, for all integers a and b ,

$$f(2a + b) = 2f(a) + f(b) \quad (1)$$

(South Africa)

Answer: The solutions are $f(n) = 0$ and $f(n) = 2n^k$ for any constant $k \in \mathbb{Z}$. Common remarks. Most

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solutions to
this problem
first prove that
f must be
linear, before

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many instructors
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Problems:

Maximum Value

Contiguous

Subsequence.

Given a sequence
of n real

numbers $A(1) \dots$

$A(n)$, determine

a contiguous

subsequence $A(i)$

$\dots A(j)$ for

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which the sum of elements in the subsequence is maximized.

Making Change.

You are given n types of coin denominations of values $v(1)$ $v(2)$ \dots $v(n)$ (all integers).

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Solution: Using
the

superposition

principle, the

force on q_3 is

$\frac{1}{3} \frac{23}{31323} \frac{2213}{23}$

$\frac{013}{23} \frac{1}{1} \hat{\hat{4}}$

$qq \quad qq \quad \pi \epsilon \quad rr \quad ()$

$= += || + () \quad FFF \quad r$

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r GGG In this case the second term will have a negative coefficient, since i is negative. The unit vectors \hat{i} and \hat{j} do not point in the same directions. In order to compute this sum,

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Boolean Algebra

Practice

Problems (do not
turn in):

Simplify each
expression by
algebraic
manipulation.

Try to recognize
when it is
appropriate to

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transform to the dual, simplify, and re-transform (e.g. no. 6).

Try doing the problems before looking at the solutions which are at the end of this problem set. 1) $a \ 0 \ + \ =$
_____14)

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general. So he gave this problem to Frobenius. In order to find a solution of this problem (which we will explain below), Frobenius created representation

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theory of finite groups. The general content of representation theory can be very briefly summarized as follows. An associative algebra over a field K is a vector space A over K equipped with

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